



Bunker flap control in steel plant



Transfer mechanism



Clarification plant  
Actuator for rake control



Flap actuator



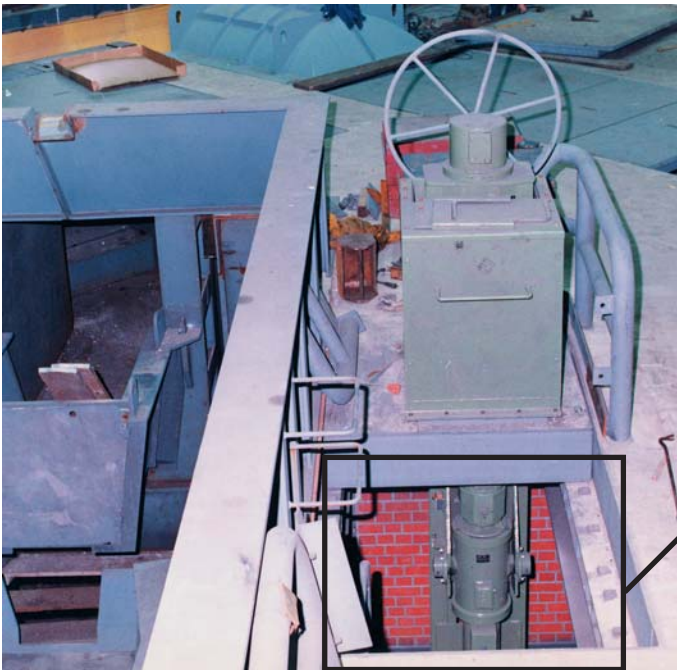
Loading mechanism  
Lignite power plant



Breches chute actuator



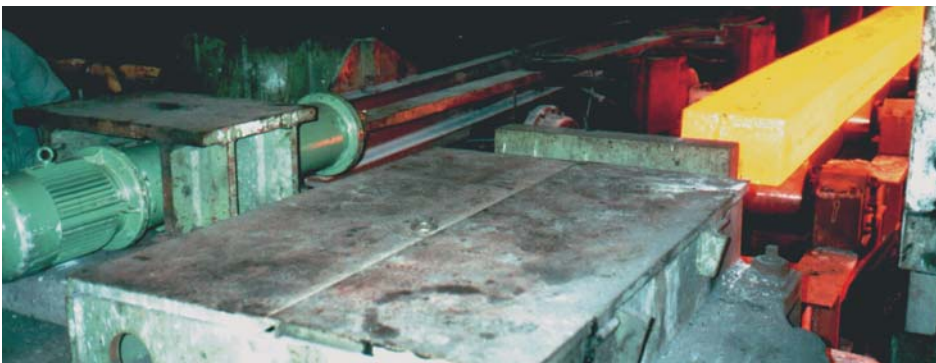
Belt scrapers for silos



Throughlike edging guide for pig iron



Governor level



Actuator for slabbing alignment

# EUBA

Antriebstechnik  
Eller GmbH  
Ruhrau 44  
D-45279 Essen

P.O. Box 14 32 07  
D-45262 Essen

Telephone +49/201/8 53 11 -0  
Telefax +49/201/8 53 11 -25  
E-Mail [info@euba.de](mailto:info@euba.de)  
Internet [www.euba.de](http://www.euba.de)



General Description	4
Attachment and Supplement	6
Technical Explanation	7
Survey of Products	9
Typeleafs	10
Piece Part Drawing and Spare Part Lists	22
Special Actuators	26
Wiring Diagrams	27
Electronical Supplement	28
Fax Request	29
Special Features	30

Our supplies and services are based on our terms of business.  
Amendments of technical data as well as of measurements and weight, specified in this catalogue, are reserved.

## General Description

EUBA - Over 40 years of Know-How in research and sale of electric actuators.

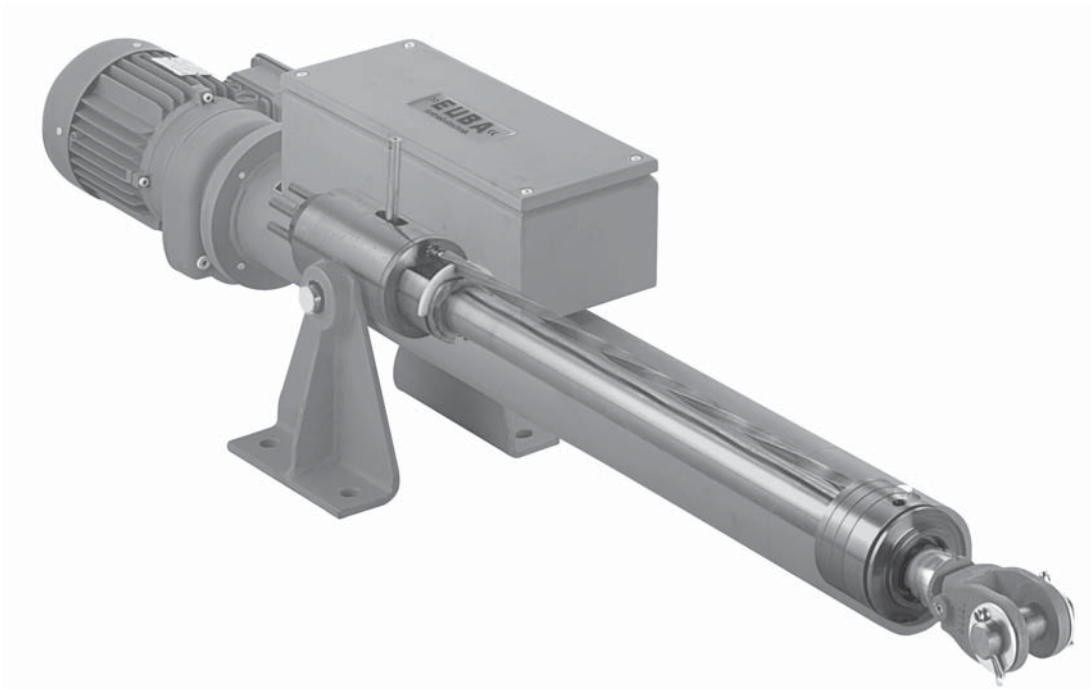
Custom-made solutions are our strength. We offer actuators from minimum of 50 daN up to mega actuators with forces up to 200.000 daN. A qualified team of engineers advises you in case of actuating problems in situ.

Innovative research and permanent quality control during manufacturing establishes standards. For your safety naturally no actuator leaves the factory until extensive examination.

From the very first beginning of your project you will be supported by qualified employees.

- ◆ Our engineering department also deals with special customer requests and offers solutions.
- ◆ Since over 40 years we manufacture our actuators with constant quality.
- ◆ Fast and professional assemblies will be done by our construction team.
- ◆ We also take on the planning and installation of the complete control engineering.

Profit by our Know-How, worldwide.



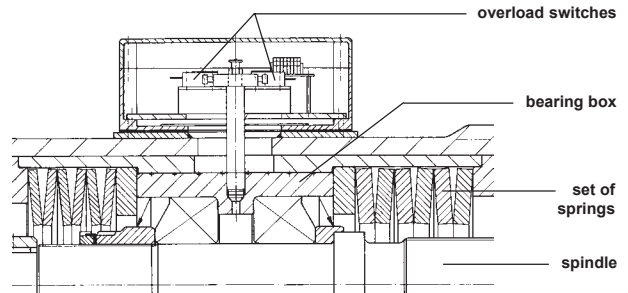
The actuators force can amount to 200.000 daN, with a stroke up to 7.000 mm and a variable velocity. Normally our actuators are manufactured with a hard chromium plated pushrod (special requests such as a ceramic plated pushrod can be considered). Commercial motor-gear combinations (A.C., D.C., et al.), which are connected to the actuator by a DIN IEC flange, are used. Rotary actuators, which are able to do complete revolutions, can also be flanged.

The base conception of this actuator is approved in heavy industry (steel plants, power plants, cement plants, et al.).

The actuator is made of a steel welded construction, sufficient dimensioned and equipped with the umpteen times proved EUBA overload switches.

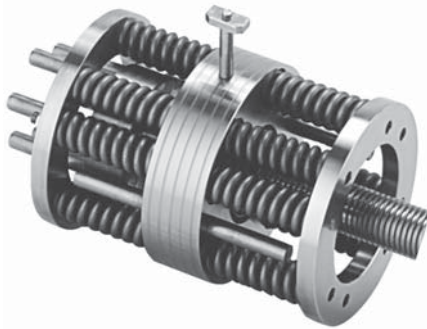
The advantages of the overload switches are:

- ◆ protection of the actuators
- ◆ absorption of axial impacts
- ◆ pressure forces can be adjusted
- ◆ wear-free attachment of motor and actuator (no slipping clutch).



Due to the variability of the spring characteristics, as well as the travel of the spring system, the overload switch is able to absorb huge axial impacts.

There is an optimal protection of the spindle against heavy loads, because the overload switch is integrated in the actuator itself.



Overload switch unit

In case of an overload of the requested push and pull forces, a shut-down of the actuator is guaranteed by overload switches.

A demolition respectively an overload of the mechanical devices is excluded from the beginning.

Due to external switch boxes the overload switches are easy accessible.

With the use of different sets of springs it is possible to adjust the overload switch to several push and pull forces and thus to specific demands.

EUBA actuators can be equipped with auxiliary attachments,

such as:

- ◆ Separat way limit switches
- ◆ Adjustable way limit switches for the whole stroke
- ◆ Overload switches
- ◆ Electronic position repeating devices 4 – 20 mA (continous)
- ◆ Bus-compatible position controller (Profibus)
- ◆ Frequency transformers
- ◆ Synchronization control for 2 or more actuators
- ◆ Synchronous speed control for 2 or more actuators

# Attachment- and Auxiliary Supplement



baseplate



threaded bold  
(external thread)



shackle  
toggle joint



angle joint with  
clamping head

limit switch  
1- or 2- polar



way limit switch

potentiometer



cardan joint

electronic position  
transmitter

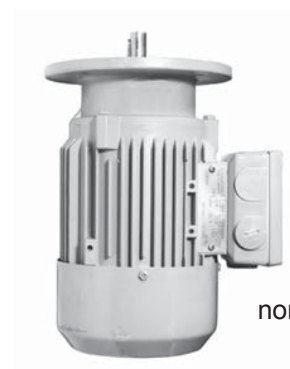


bracket  
for pivot

switch box  
incl.  
overload unit



brake motor



norm motor

handwheel  
with or without electrical shutdown



Yoke end

gear motor

# Technical Explanation

## Calculations:

### 1. Determination of push-pull forces

For the calculations of push-pull forces for **EUBA**-actuators you have to consider the acceleration factors as specified in the chart below. This leads to the following calculation models:

a) Horizontal movement    b) Vertical movement

$$F_B = m \cdot a = \frac{G}{g} \cdot a \qquad F = F_B + F_R + G$$

$$F_R = \mu \cdot G$$

$$F = F_B + F_R$$

- $F_B$  = acceleration force [N]
- $m$  = body weight [kg]
- $a$  = acceleration [m/s<sup>2</sup>]
- $G$  = load [N]
- $g$  = gravitational force [m/s<sup>2</sup>]
- $F_R$  = frictional force [N]
- $\mu$  = coefficient of friction
- $F$  = necessary force of EUBA-actuator [N]

### 2. Acceleration factors

According to the specific velocity you have to use the following acceleration factors as an average value:

v [mm/s]	25	45	75	90	120	150	175	180
a [m/s <sup>2</sup> ]	1	2	3	4	5	6	7	8

### 3. Operating frequency

The operating frequency (s/min) of the EUBA-actuators depend on the maximum switching operations of the commercial motors and its electrical self-heating.

Based on years of experience, the maximum operating frequency of the EUBA-actuators meets half of the maximum no-load switchings of the motor per minute.

Hence we may infer the following average values :

P [kW]	0,09	0,12	0,18	0,25	0,37	0,55	0,75
s [1/min]	35	35	30	25	25	20	20

P [kW]	1,1	1,5	2,2	3	4	5,5	7,5
s [1/min]	18	15	15	10	8	6	6

Above given data is meant for  $n=1500 \text{ min}^{-1}$  and a maximum ambient temperature of  $t=40^\circ \text{ C}$ .

The operating frequency depends on stroke and velocity also.

### Attention:

A motor-switch over from a left-handed into a right-handed rotation or vice versa is not allowed without a shutdown of the motor itself.

For special environmental and aggressive conditions EUBA-actuators can be sandblasted according to SA 2,5 and can be varnished with a coating thickness up to 240 µm.

For the case the actuators are used in explosion hazardous plants, an application of way limit- and overload switches in Ex-i as well as three phase motors in the prescribed protection class is required.

Protection class IP-55 is the standard of all EUBA-actuators, but they are available up to protection class IP-68 on request.

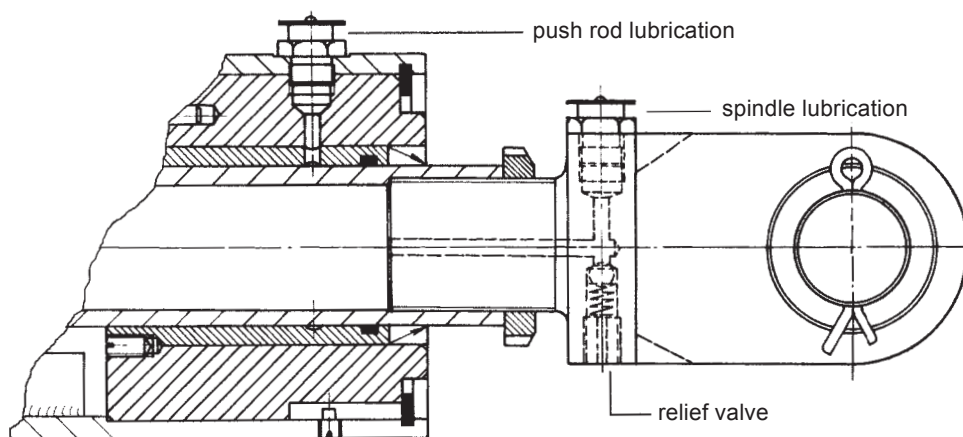
For an operation of the actuator during power failure we recommend a handwheel. For these actuators, the motor shaft protrudes at the end. It is possible to equip the motor shaft with a handwheel or a crank.

If demanded an electrical shutdown of the motor can be ensued when the handwheel is attached. The vacant second motor shaft is covered with a protection rod during normal operation all the time.

Depending on the requirements EUBA-actuators are equipped with different lubricants. The specifications of the used lubricants can be found in the operation and maintenance manual.

Usually the actuators are filled with Li-EP 2 grease.

The maintenance of the EUBA-actuators is limited to regular relubrication of the spindle nut-system. An excess pressure protection impedes an over-lubrication of the actuator.



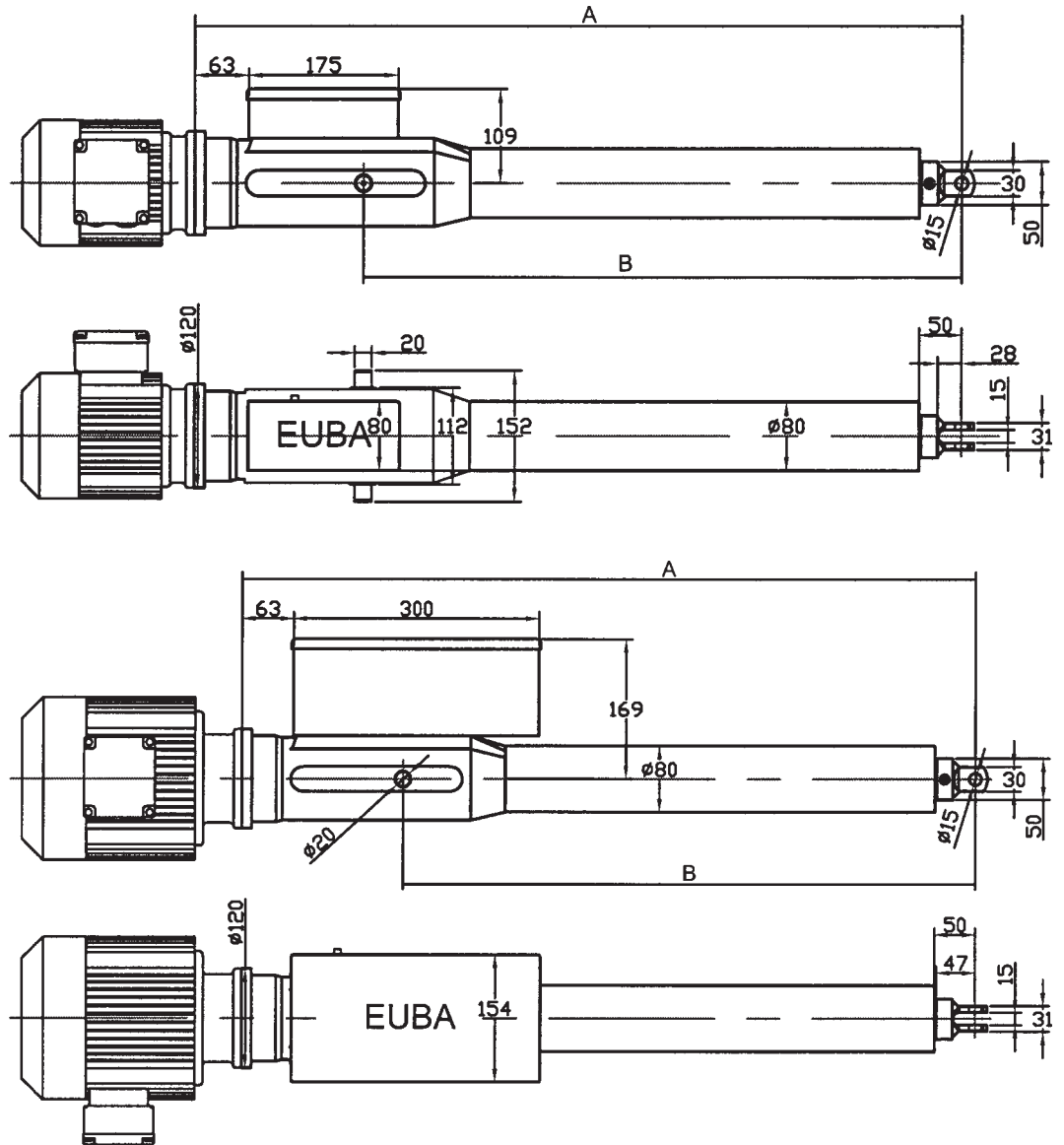
## Survey of Products Standard Design

<b>EUBA-Typ</b>	<b>max. force F up to</b>	<b>max. velocity v up to</b>	<b>max. stroke up to</b>	<b>page</b>
A 4	500 daN	90 mm/s	600 mm	10
B 4	2.500 daN	180 mm/s	1.250 mm	13
C 4	4.500 daN	120 mm/s	2.500 mm	16
D 4	15.000 daN	60 mm/s	4.000 mm	19
E 4	50.000 daN	30 mm/s	4.000 mm	30
F 4*	200.000 daN	10 mm/s	4.000 mm	30

\* on request

**For the determination of forces, please consider calculations on page 7!**

## Type A4:



Mounting dimension actuator in mm (weight: 25-35 kg)													
stroke	0	50	100	150	200	250	300	350	400	450	500	550	600
A-size	397	447	497	547	597	647	697	747	797	847	897	947	997
B-size	206	256	306	356	406	456	506	576	626	676	726	776	826

Actuator dimensions can vary, especially the motor dimensions due to different brands.

B-size changeable (+/- 100 mm)

Motor dimensions depending on motor type and supplier

**Power chart:**

P in kW in accordance with DIN IEC							
v in mm/s		5	25	45	63	70	94
F in daN	100	0,09	0,12	0,18	0,18	0,25	0,37
	200	0,09	0,18	0,37	0,37	0,55	0,55
	300	0,09	0,25	0,55	0,55	0,75	1,10
	400	0,09	0,37	0,55	0,75	1,10	1,10
	500	0,12	0,37	0,75	1,10	1,10	1,50

Forces in between min. and max. can be realised continuously.

**Standard design:**

- Pivot
- Clevis

**Special design:**

- Brackets
- Foot mounting
- Cardan joint
- Special fixing
- Shackle toggle joint
- Angle ball

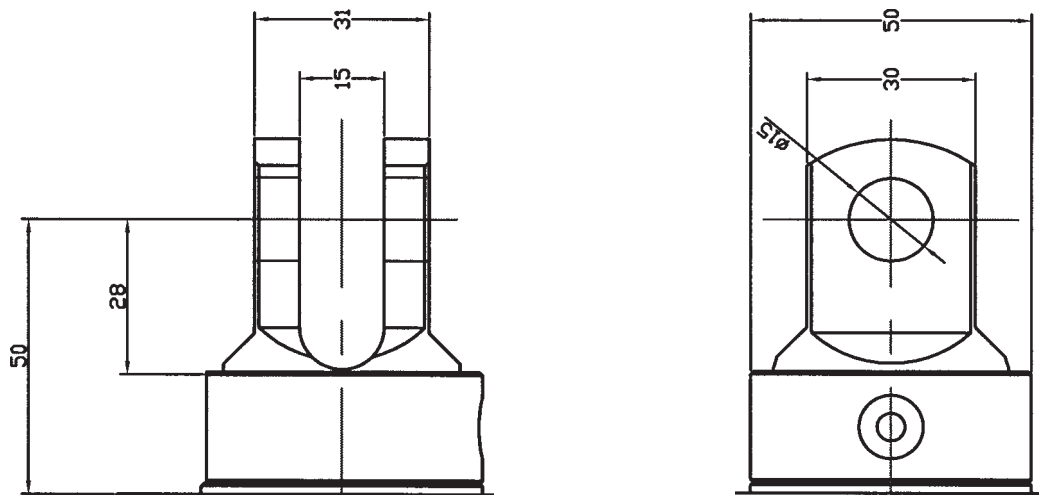
**Actuator:**

- Steel, with overload switches
- Acme screw thread spindle
- Spindle bearing system, on both sides supported by spring piles
- Chrome plated push rod with internal torsion protection

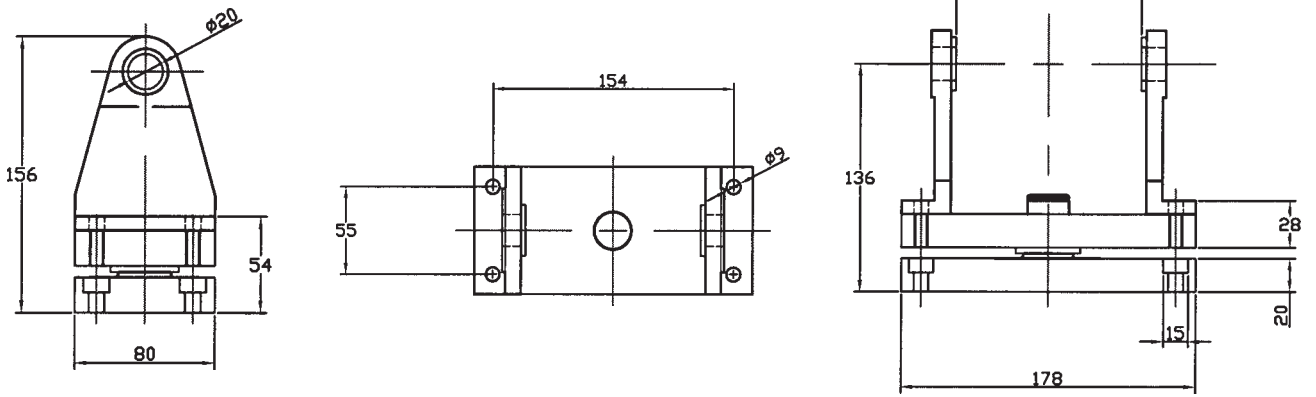
**Motor:**

Attachment of DIN IEC flange- and gear motors

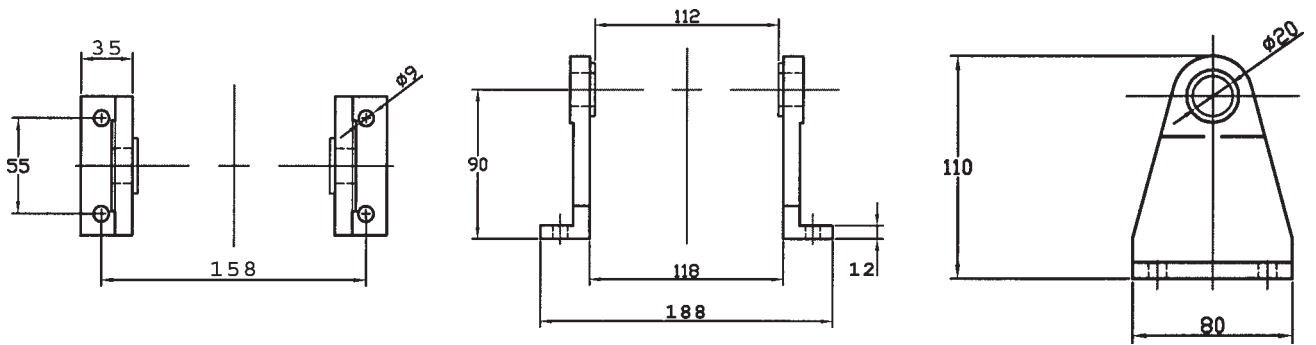
**Clevis:**



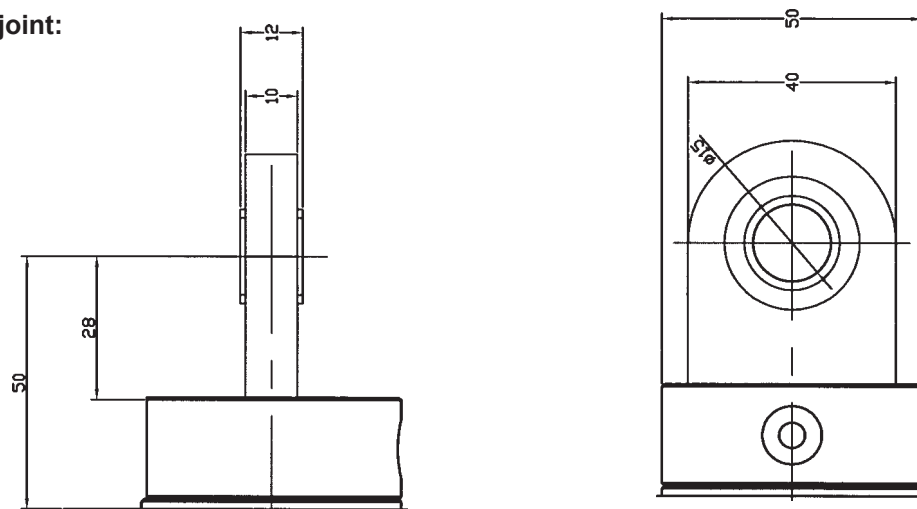
**Cardan joint:**



**Brackets for pivot:**

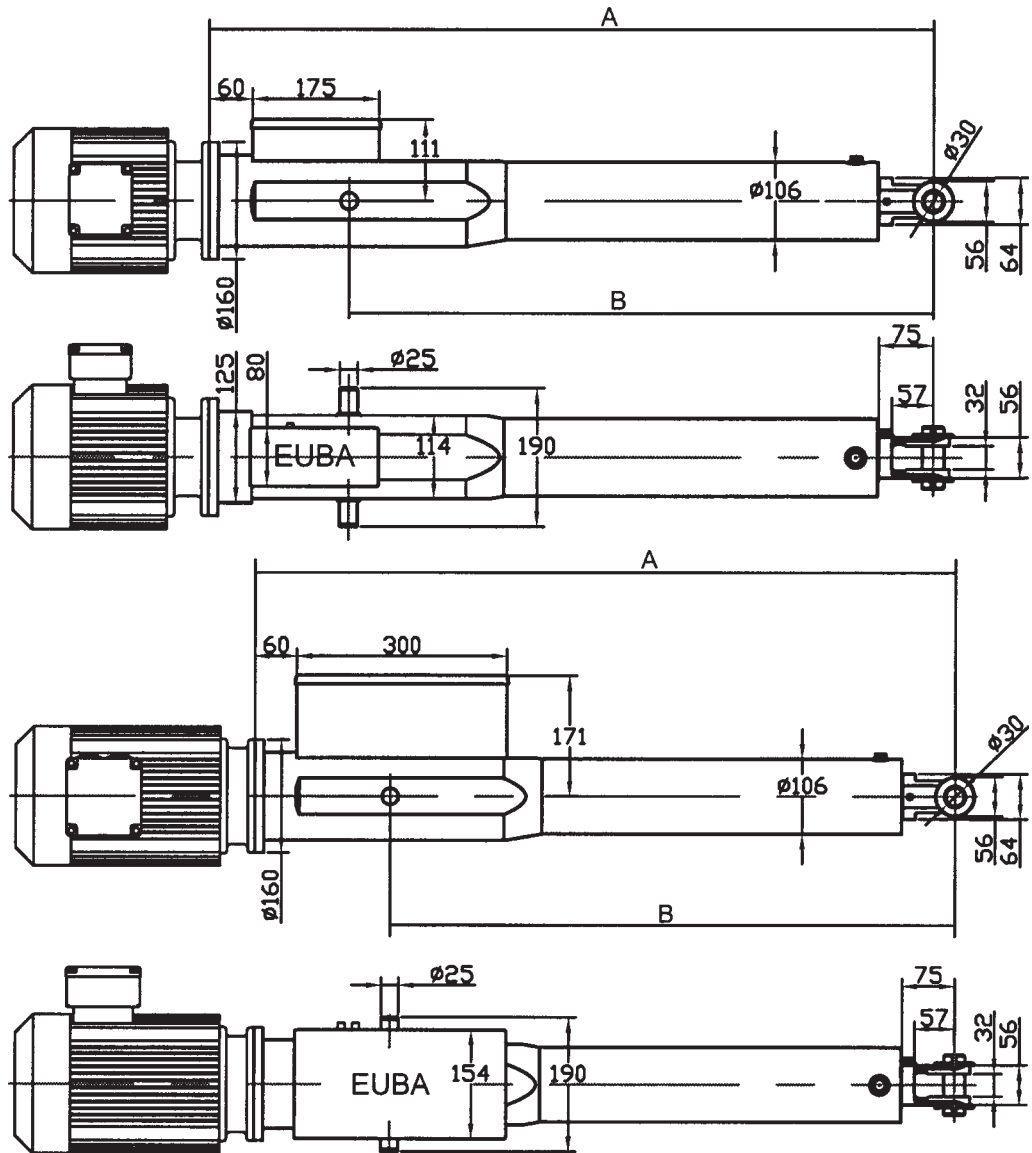


**Shackle toggle joint:**



Please use Fax request sheet on page 29 for a detailed technical layout.  
 Minor changes in dimensions are possible due to production tolerances.

## Type B4:



Mounting dimension actuator in mm (weight: 60-80 kg)													
<b>stroke</b>	0	50	100	150	200	250	300	350	400	450	500	550	600
<b>A-size</b>	502	552	602	652	702	752	802	852	902	952	1002	1052	1102
<b>B-size</b>	308	358	408	458	508	558	608	658	708	758	808	858	908
<b>stroke</b>	650	700	750	800	850	900	950	1000	1050	1100	1150	1200	1250
<b>A-size</b>	1152	1202	1252	1302	1352	1402	1452	1502	1552	1602	1652	1702	1752
<b>B-size</b>	958	1008	1058	1108	1158	1208	1258	1308	1358	1408	1458	1508	1558

Actuator dimensions can vary, especially the motor dimensions due to different brands.

B-size changeable (+/- 100 mm)

Motor dimensions depending on motor type and supplier

**Power chart:**

P in kW in accordance with DIN IEC								
v in mm/s		5	25	40	63	80	94	118
F in daN	500	0,09	0,37	0,75	1,10	1,50	1,50	2,20
	750	0,12	0,55	1,10	1,50	2,20	2,20	3,00
	1000	0,18	0,75	1,50	2,20	-	3,00	4,00
	1500	0,25	1,10	2,20	-	-	-	-
	2000	0,37	1,50	3,00	-	-	-	-
	2500	0,37	2,20	3,00	-	-	-	-

Forces in between min. and max. can be realised continuously.

**Standard design:**

- Pivot
- Clevis

**Special design:**

- Brackets
- Foot mounting
- Cardan joint
- Special fixing
- Shackle toggle joint
- Angle ball

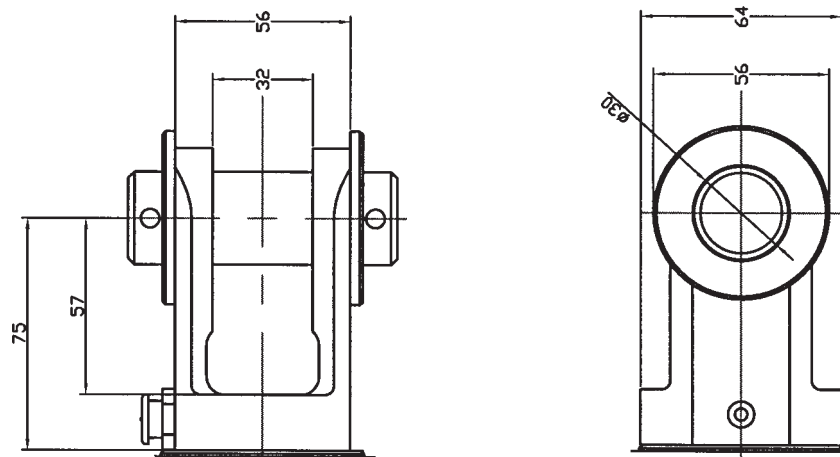
**Actuator:**

- Steel, with overload switches
- Acme screw thread spindle
- Spindle bearing system, on both sides supported by spring piles
- Chrome plated push rod with internal torsion protection

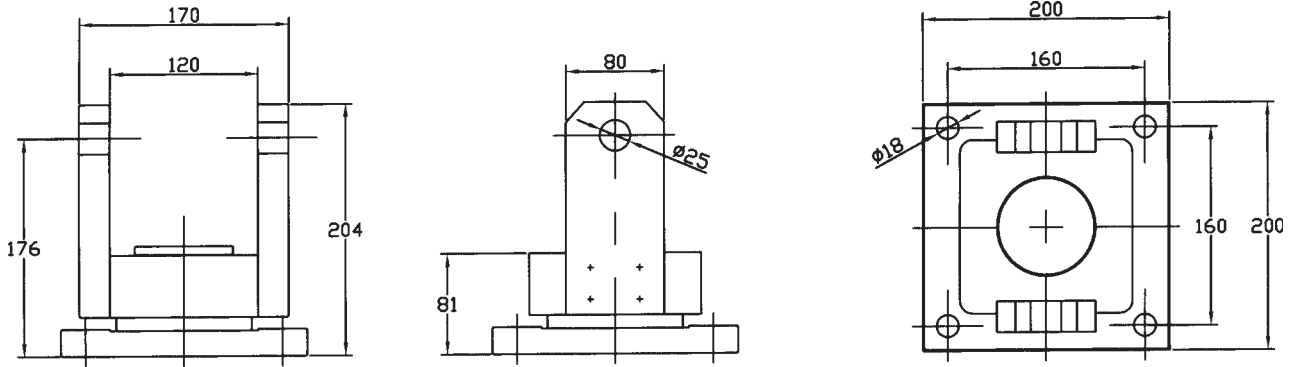
**Motor:**

Attachment of DIN IEC flange- and gear motors (manufacturer independent)

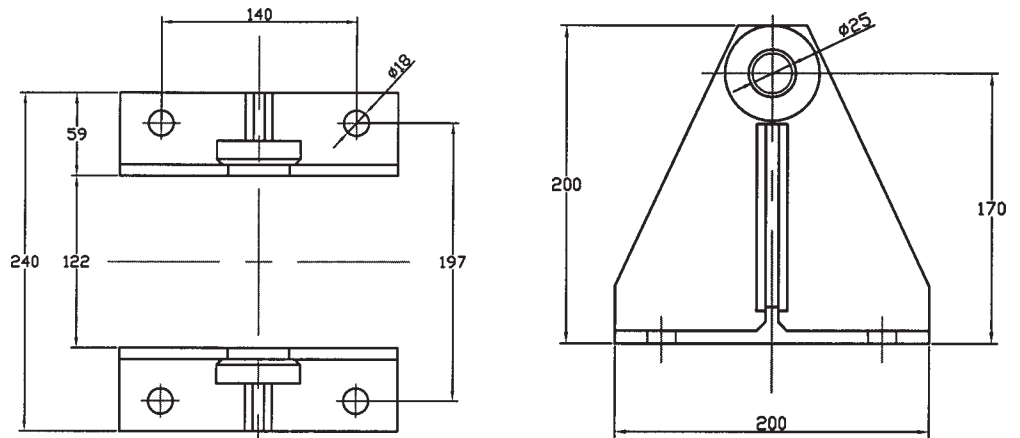
**Clevis:**



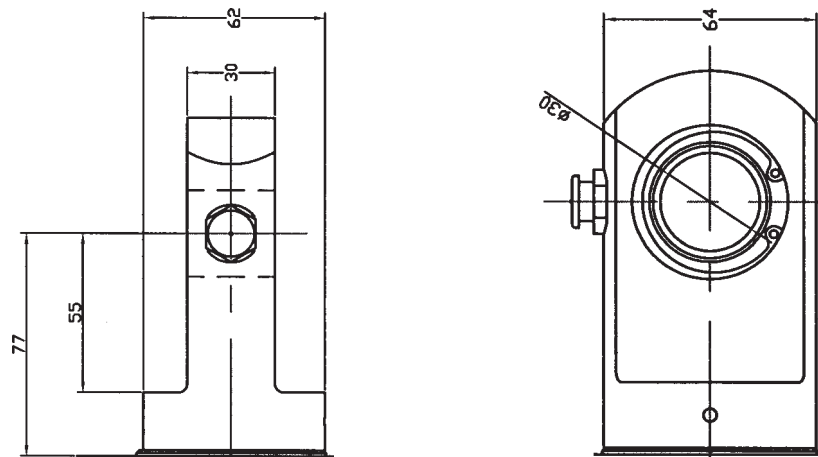
**Cardan joint:**



**Brackets for pivot:**

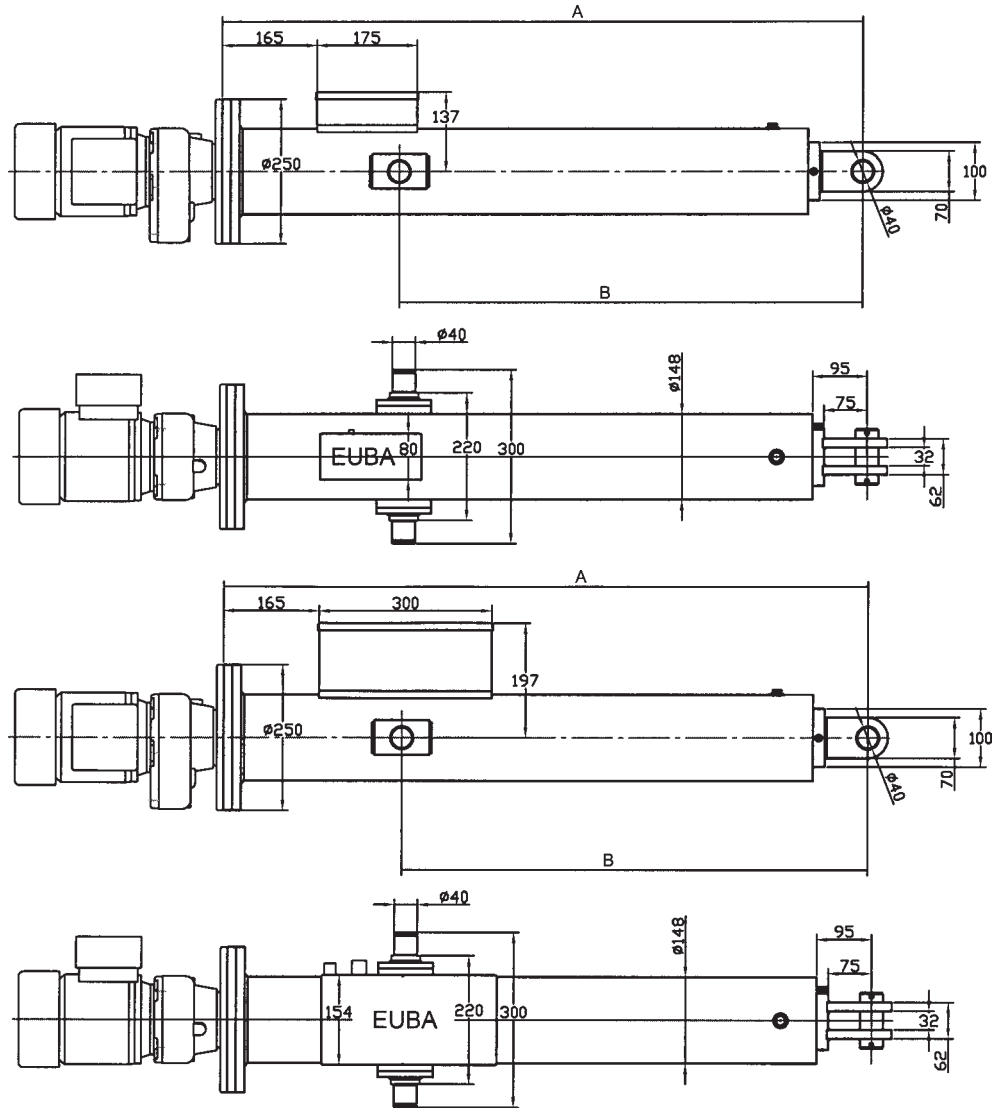


**Shackle toggle joint:**



Please use Fax request sheet on page 29 for a detailed technical layout.  
 Minor changes in dimensions are possible due to production tolerances.

## Type C4:



Mounting dimension actuator in mm (weight: 120-250 kg)																
<b>stroke</b>	0	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750
<b>A-size</b>	618	668	718	768	818	868	918	968	1018	1068	1118	1168	1218	1268	1318	1368
<b>B-size</b>	180	230	280	330	380	430	500	550	600	650	700	750	800	850	900	950
<b>stroke</b>	800	850	900	950	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	
<b>A-size</b>	1418	1468	1518	1568	1618	1668	1718	1768	1818	1868	1918	1968	2018	2068	2118	
<b>B-size</b>	1000	1050	1100	1150	1200	1250	1300	1350	1400	1450	1500	1550	1600	1650	1700	

Actuator dimensions can vary, especially the motor dimensions due to different brands.

B-size changeable (+/- 100 mm)

Motor dimensions depending on motor type and supplier

**Power chart:**

P in kW in accordance with DIN IEC								
v in mm/s		5	15	25	35	45	111	166
F in daN	1500	0,25	0,75	1,10	2,20	2,20	5,50	7,50
	2000	0,37	1,10	1,50	2,20	3,00	-	-
	2500	0,55	1,50	2,20	3,00	4,00	-	-
	3000	0,55	1,50	3,00	4,00	4,00	-	-
	4000	0,75	2,20	3,00	5,50	5,50	-	-
	5000	0,75	3,00	4,00	5,50	7,50	-	-

Forces in between min. and max. can be realised continuously.

**Standard design:**

- Pivot
- Clevis

**Special design:**

- Brackets
- Foot mounting
- Special fixing
- Shackle toggle joint
- Angle ball

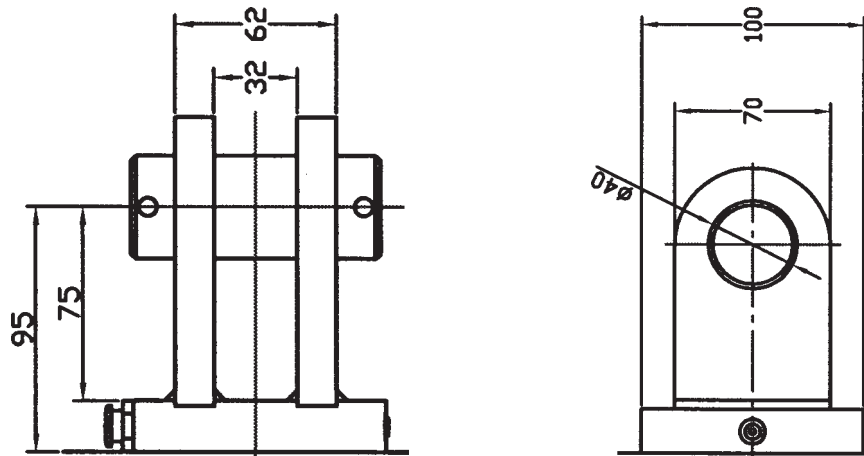
**Actuator:**

- Steel, with overload switches
- Acme screw thread spindle
- Spindle bearing system, on both sides supported by spring piles
- Chrome plated push rod with internal torsion protection

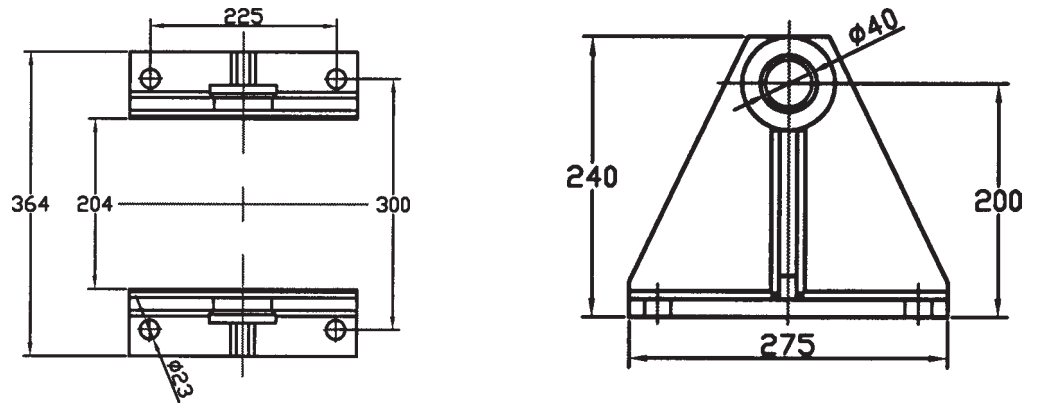
**Motor:**

Attachment of DIN IEC flange- and gear motors (manufacturer independent)

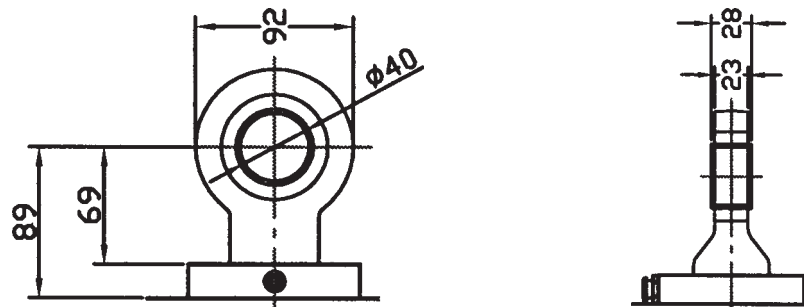
**Clevis:**



Brackets for pivot:

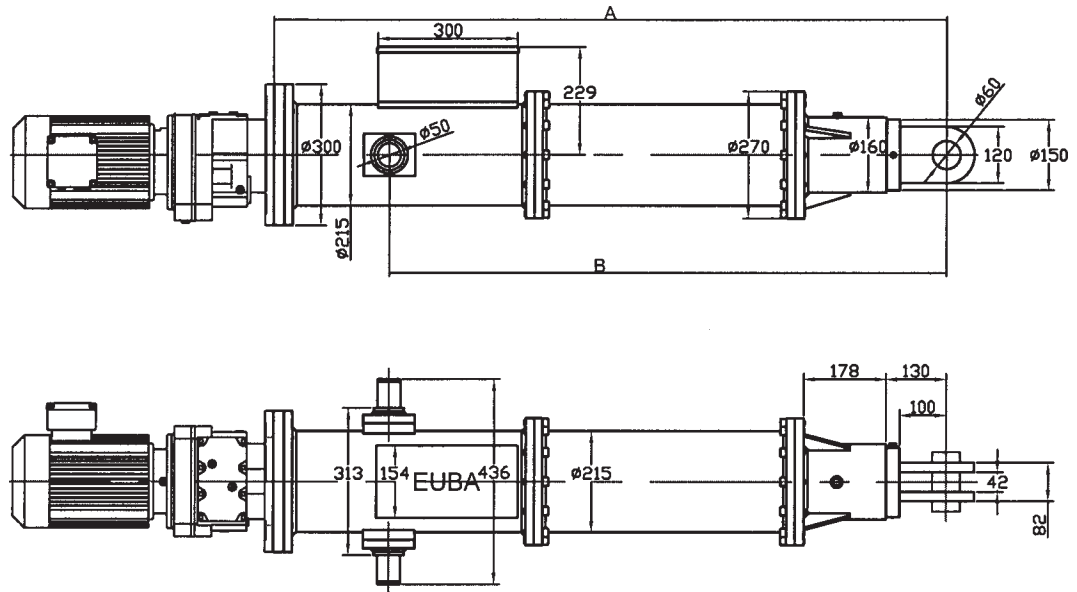


Shackle toggle joint:



Please use Fax request sheet on page 29 for a detailed technical layout.  
Minor changes in dimensions are possible due to production tolerances.

## Type D4:



Mounting dimension actuator in mm (weight: 150-400 kg)																
stroke	0	50	100	150	200	250	300	350	400	450	500	550	600	650	700	750
<b>A-size</b>	988	1038	1088	1138	1188	1238	1288	1338	1388	1438	1488	1538	1588	1638	1688	1738
<b>B-size</b>	699	749	799	849	899	949	999	1049	1099	1149	1199	1249	1299	1349	1399	1449
<b>stroke</b>	800	850	900	950	1000	1100	1200	1300	1400	1500	1600	1700	1800	1900	2000	
<b>A-size</b>	1788	1838	1888	1938	1988	2088	2188	2288	2388	2488	2588	2688	2788	2888	2988	
<b>B-size</b>	1499	1549	1599	1649	1699	1799	1899	1999	2099	2199	2299	2399	2499	2599	2699	

Actuator dimensions can vary, especially the motor dimensions due to different brands.

B-size changeable (+/- 100 mm)

Motor dimensions depending on motor type and supplier

**Power chart:**

		P in kW in accordance with DIN IEC						
v in mm/s		5	15	25	35	40	50	60
F in daN	4000	0,75	2,20	4,00	5,50	7,50	7,50	9,20
	6000	1,10	4,00	5,50	7,50	9,20	11,00	15,00
	8000	1,50	5,50	7,50	11,00	15,00	15,00	18,50
	10000	2,20	5,50	9,20	15,00	15,00	18,50	22,00
	12500	2,20	7,50	11,00	18,50	18,50	22,00	30,00
	15000	3,00	9,20	15,00	18,50	22,00	30,00	-

Forces in between min. and max. can be realised continuously.

**Standard design:**

- Pivot
- Clevis

**Special design:**

- Brackets
- Foot mounting
- Cardan joint
- Special fixing
- Shackle toggle joint
- Angle ball

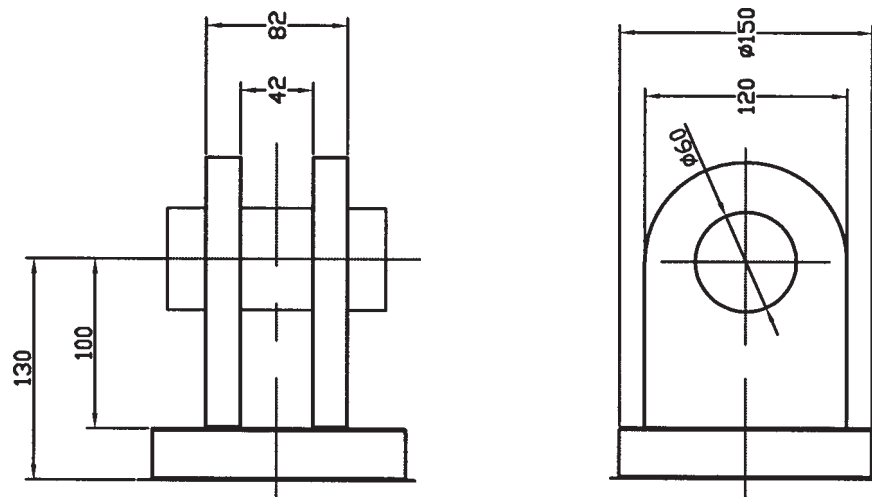
**Actuator:**

- Steel, with overload switches
- Acme screw thread spindle
- Spindle bearing system, on both sides supported by spring piles
- Chrome plated push rod with internal torsion protection

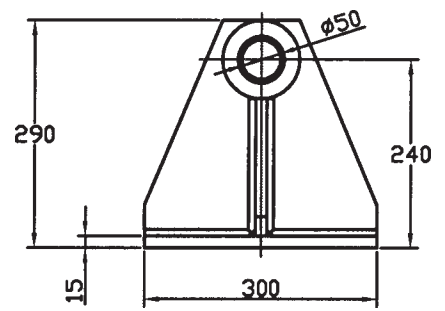
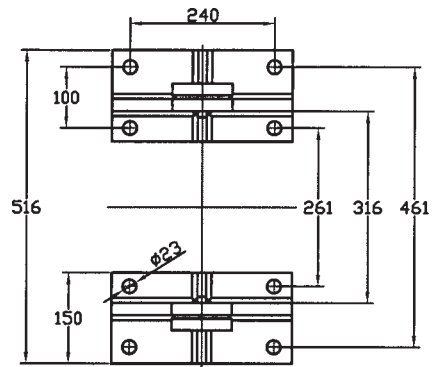
**Motor:**

Attachment of DIN IEC flange- and gear motors (manufacturer independent)

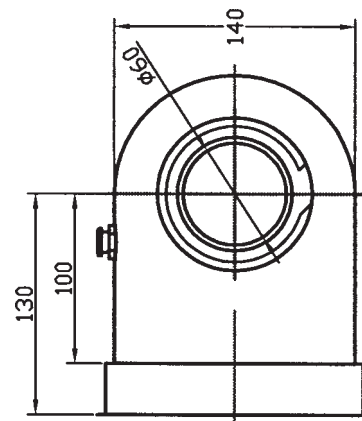
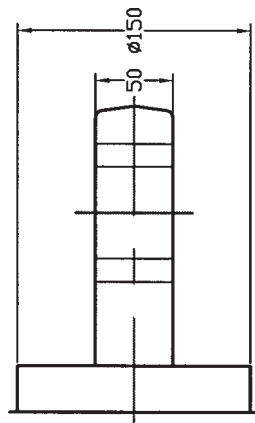
**Clevis:**



**Brackets for pivot:**



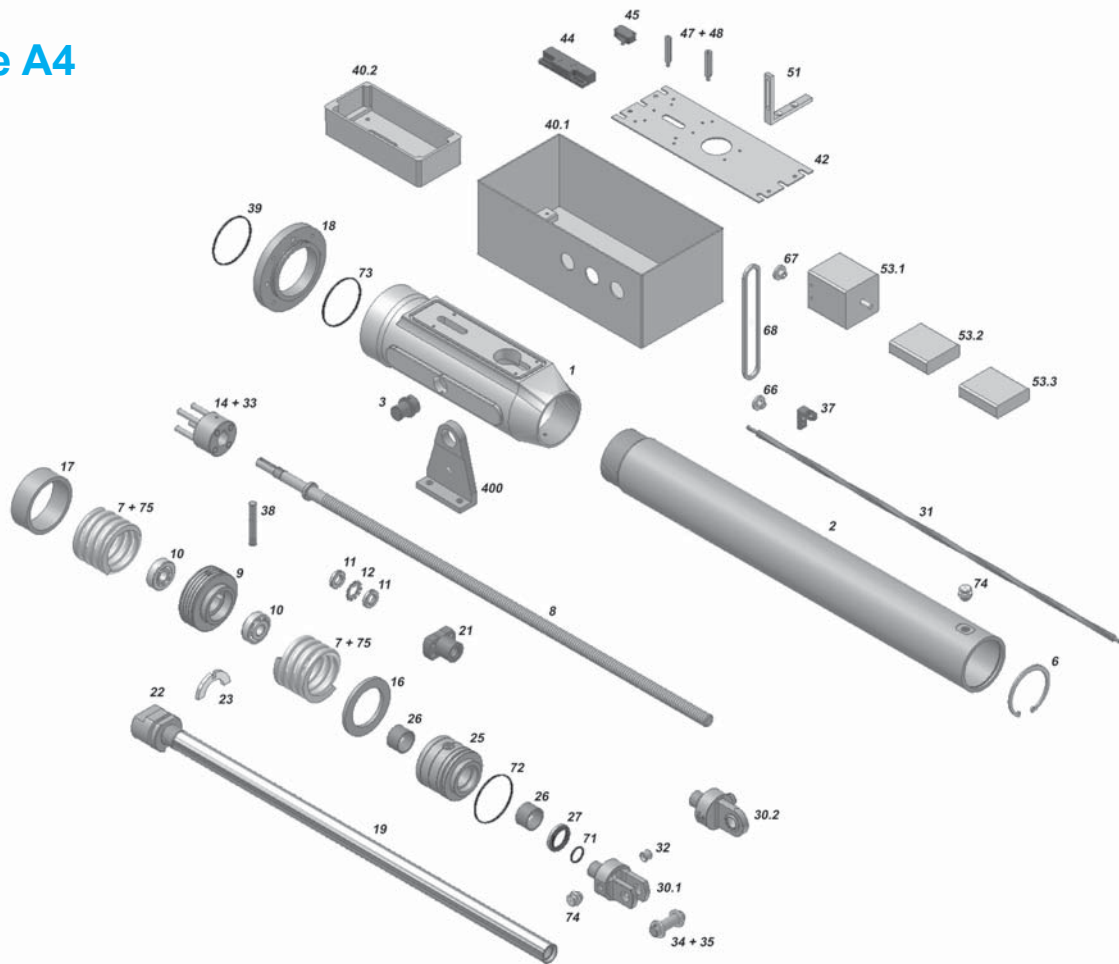
**Shackle toggle joint:**



Please use Fax request sheet on page 29 for a detailed technical layout.  
Minor changes in dimensions are possible due to production tolerances.

## Spare parts drawing of EUBA-actuators

### Type A4



Object	Pc's	Description	Object	Pc's	Description
1	1	Overload housing	31	1	Torsion rod
2	1	Rod housing	32	1	Pressure safety
3	2	Turning pin	34 + 35	1	Yoke end bolt + washer
6	1	Lock ring	37	1	Angle for torsion rod
7	Set	Cup spring	38	1	Switching piece
8	1	Acme thread spindle	39*	1	O-Ring rear flange
9	1	Bearing housing	40.1	1	Switch box complete
10*	2	Tapered roller bearing	40.2	1	Overload switch box complete
11*	2	Shaft nut	42	1	Mounting board
12*	1	Safety sheet	44	2	Micro end switch board
14 + 33	2	Coupling	45*	Set	Micro end switches
16	2	Thrust ring	47+ 48	2	Distance bolt + rail
17	1	Spacer sleeve	51	1	Angle for way limit switch
18	1	Flange	53.1	1	Way limit switch
19	1	Push rod	53.2	1	Potentiometer
21*	1	Acme spindle nut	53.3	1	Electronic position transmitter
22	1	Push rod head	66	1	Roller chain sprocket
23*	1	Torsion rod guide	67	1	Roller chain sprocket
25	1	Push rod guide	68*	1	Roller chain
26*	2	Bushing guide	71*	1	O-Ring jocke end
27*	1	Scraper	72*	1	O-Ring bushing guide
30.1	1	Yoke end	73*	1	O-Ring front flange
30.2	1	Shackle toggle joint	74*	2	Flat grease nipple
			75	6	Spacer ring
			400	2	Brackets

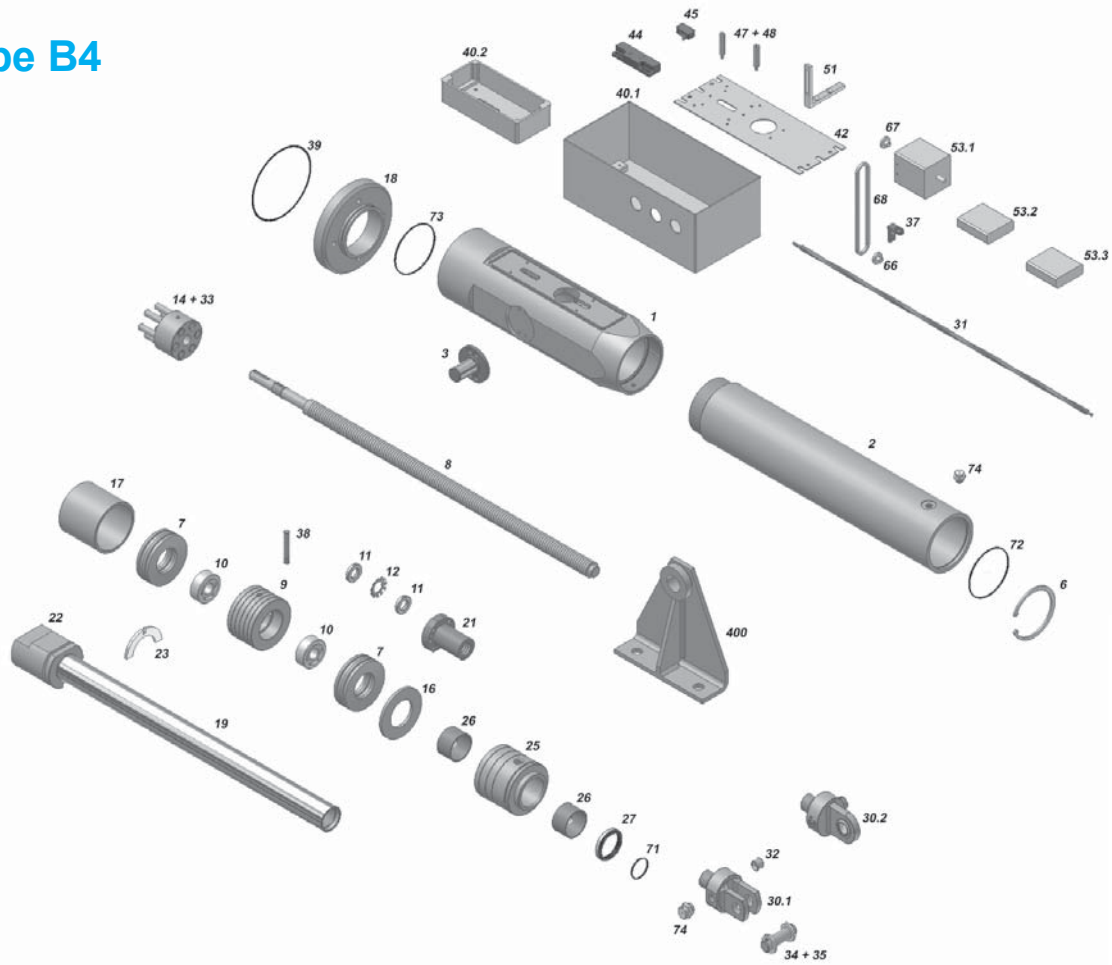
\* = wear out parts

Please indicate actuator number as well as the position of the spare part list.

For online spare parts enquiries please go to [www.euba.de](http://www.euba.de)

## Spare parts drawing of EUBA-actuators

### Type B4



Object	Pc's	Description	Object	Pc's	Description
1	1	Overload housing	31	1	Torsion rod
2	1	Rod housing	32	1	Pressure safety
3	2	Turning pin	34 + 35	1	Yoke end bolt + washer
6	1	Lock ring	37	1	Angle for torsion rod
7	Set	Cup spring	38	1	Switching piece
8	1	Acme thread spindle	39*	1	O-Ring rear flange
9	1	Bearing housing	40.1	1	WS-Switch box complete
10*	2	Tapered roller bearing	40.2	1	Overload switch box complete (-DE-)
11*	2	Shaft nut	42	1	Mounting board
12*	1	Safety sheet	44	2	Micro end switch board
14 + 33	2	Coupling	45*	Set	Micro end switches
16	2	Thrust ring	47+ 48	2	Distance bolt + rail
17	1	Spacer sleeve	51	1	Angle for way limit switch
18	1	Flange	53.1	1	Way limit switch -WS...-
19	1	Push rod	53.2	1	Potentiometer
21*	1	Acme spindle nut	53.3	1	Electronic position transmitter (4/20 mA)
22	1	Push rod head	66	1	Roller chain sprocket
23*	1	Torsion rod guide	67	1	Roller chain sprocket
25	1	Push rod guide	68*	1	Roller chain
26*	2	Bushing guide	71*	1	O-Ring yoke end
27*	1	Scraper	72*	1	O-Ring bushing guide
30.1	1	Yoke end	73*	1	O-Ring front flange
30.2	1	Shackle toggle joint	74*	2	Flat grease nipple
			400	2	Brackets

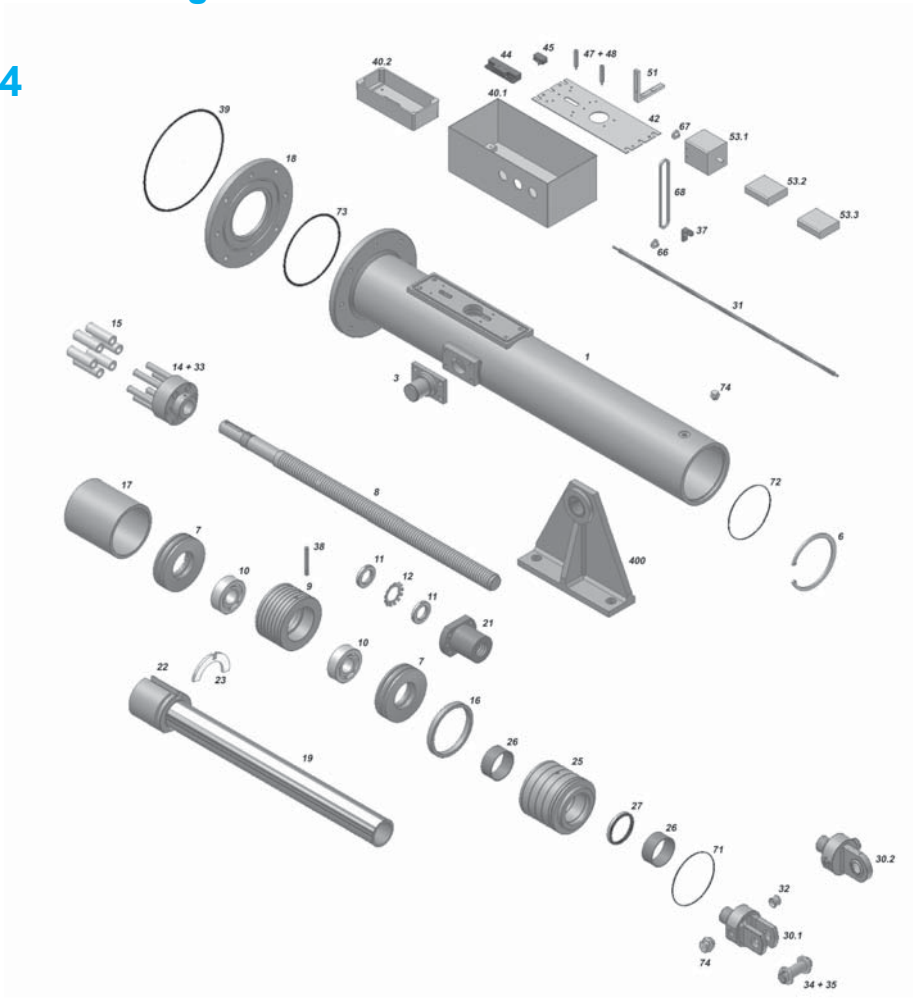
\* = wear out parts

Please indicate actuator number as well as the position of the spare part list.

For online spare parts enquiries please go to [www.euba.de](http://www.euba.de)

## Spare parts drawing of EUBA-actuators

### Type C4



Object	Pc's	Description	Object	Pc's	Description
1	1	Housing	31	1	Torsion rod
3	2	Turning pin	32	1	Pressure safety
6	1	Lock ring	34 + 35	1	Yoke end bolt + washer
7	Set	Cup spring	37	1	Angle for torsion rod
8	1	Acme thread spindle	38	1	Switching piece
9	1	Bearing housing	39*	1	O-Ring rear flange
10*	2	Tapered roller bearing	40.1	1	WS-Switch box complete
11*	2	Shaft nut	40.2	1	Overload switch box complete (-DE-)
12*	1	Safety sheet	42	1	Mounting board
14 + 33	2	Coupling	44	2	Micro end switch board
15	Set	Coupling buffer	45*	Set	Micro end switches
16	2	Thrust ring	47+ 48	2	Distance bolt + rail
17	1	Spacer sleeve	51	1	Angle for way limit switch
18	1	Flange	53.1	1	Way limit switch
19	1	Push rod	53.2	1	Potentiometer
21*	1	Acme spindle nut	53.3	1	Electronic position transmitter (4/20 mA)
22	1	Push rod head	66	1	Roller chain sprocket
23*	1	Torsion rod guide	67	1	Roller chain sprocket
25	1	Push rod guide	68*	1	Roller chain
26*	2	Bushing guide	71*	1	O-Ring joke end
27*	1	Scraper	72*	1	O-Ring bushing guide
30.1	1	Yoke end	73*	1	O-Ring front flange
30.2	1	Shackle toggle joint	74*	2	Flat grease nipple
			400	2	Brackets

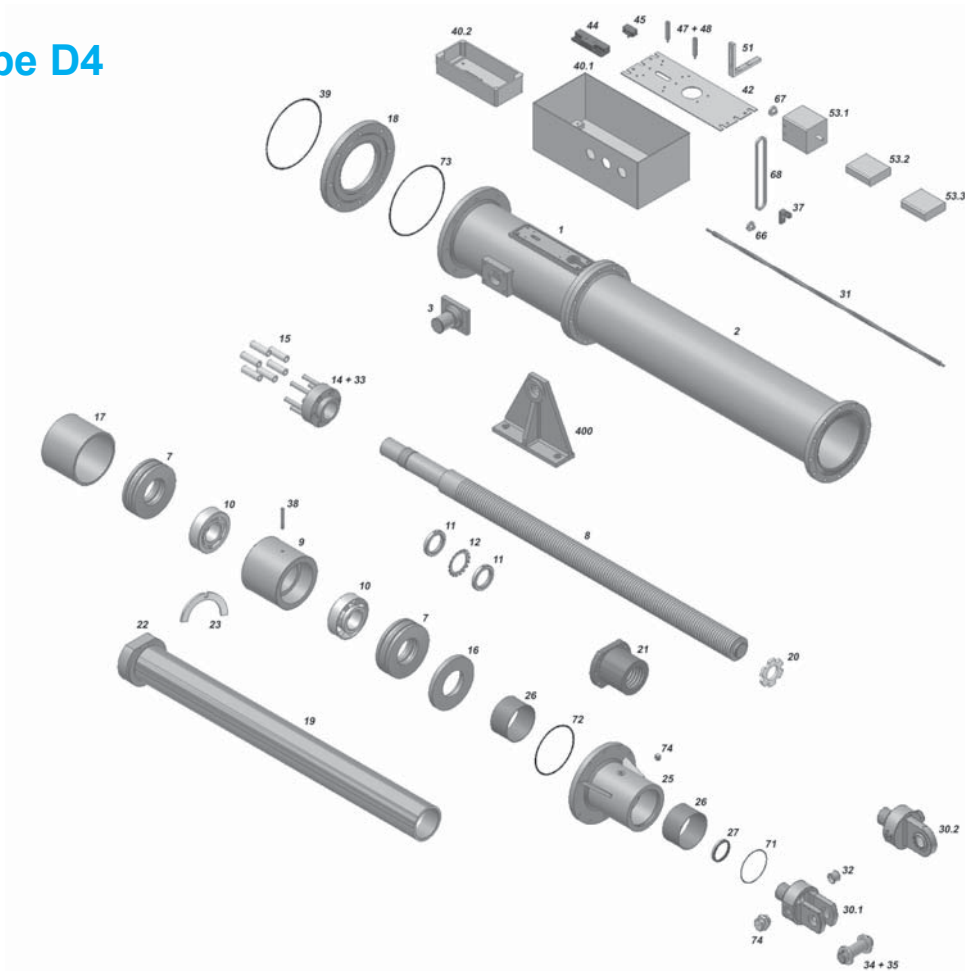
\* = wear out parts

Please indicate actuator number as well as the position of the spare part list.

For online spare parts enquiries please go to [www.euba.de](http://www.euba.de)

## Spare parts drawing of EUBA-actuators

### Type D4



Object	Pc's	Description	Object	Pc's	Description
1	1	Housing	31	1	Torsion rod
3	2	Turning pin	32	1	Pressure safety
7	Set	Cup spring	34 + 35	1	Yoke end bolt + washer
8	1	Acme thread spindle	37	1	Angle for torsion rod
9	1	Bearing housing	38	1	Switching piece
10*	2	Tapered roller bearing	39*	1	O-Ring rear flange
11*	2	Shaft nut	40.1	1	Switch box complete
12*	1	Safety sheet	40.2	1	Overload switch box complete
14 + 33	2	Coupling	42	1	Mounting board
15	Set	Coupling buffer	44	2	Micro end switch board
16	2	Thrust ring	45*	Set	Micro end switches
17	1	Spacer sleeve	47+ 48	2	Distance bolt + rail
18	1	Flange	51	1	Angle for way limit switch
19	1	Push rod	53.1	1	Way limit switch
20	1	Acme thread spindle buffer	53.2	1	Potentiometer
21*	1	Acme spindle nut	53.3	1	Electronic position transmitter
22	1	Push rod head	66	1	Roller chain sprocket
23*	1	Torsion rod guide	67	1	Roller chain sprocket
25	1	Push rod guide	68*	1	Roller chain
26*	2	Bushing guide	71*	1	O-Ring joke end
27*	1	Scraper	72*	1	O-Ring bushing guide
30.1	1	Yoke end	73*	1	O-Ring front flange
30.2	1	Shackle toggle joint	74*	2	Flat grease nipple
			400	2	Brackets

\* = wear out parts

Please indicate actuator number as well as the position of the spare part list.

For online spare parts enquiries please go to [www.euba.de](http://www.euba.de)

---

## Special Actuators:

### Actuators type W:

These actuators are specially designed for hydro engineering. The prescriptions of the DIN-standards for these actuators are realized by a special assembly.

The range of application of our actuators are docks, flood gates, water works and purification plants (see page 32).

### Special designed actuators:

#### Throughlike edging guide actuators:

It is possible to adjust throughlike edging guides for all kinds with these actuators, e.g. for pig iron or slag. As a result high forces with small velocities can be fabricated also (see center page 2).

#### Ingot pusher:

Actuators of this kind can be used at industrial furnaces, foundry plants et al., where high forces, strokes and velocity are needed.

#### Road blocker:

Suitable for driveways, carparks or city entrances. The characteristic of this actuator is an automatic retraction during a power failure. Individual control panels, including key switches or remote controls for police-, fire departments and ambulances, for an automatic opening or closing for driveways can be installed (see page 31 down left).

#### Gate actuators:

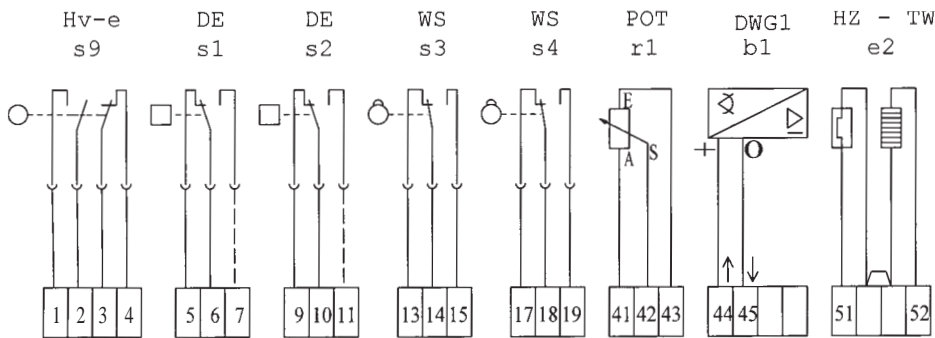
Special designed actuators for opening and closing of heavy gates with long strokes. Strokes of 7 m can be realized with only one motor and two stroke units (see center page 31).

#### Window actuators:

With only one EUBA-actuator you are able to open and close columns of windows. Greenhouses, hangars, farmhouses or buildings with glass domes can be equipped with thermal sensors for an automatical control of the inside temperature.

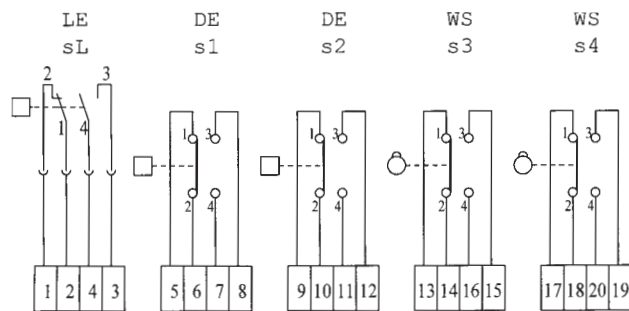
# Wiring Diagrams

## Switches 1-polar

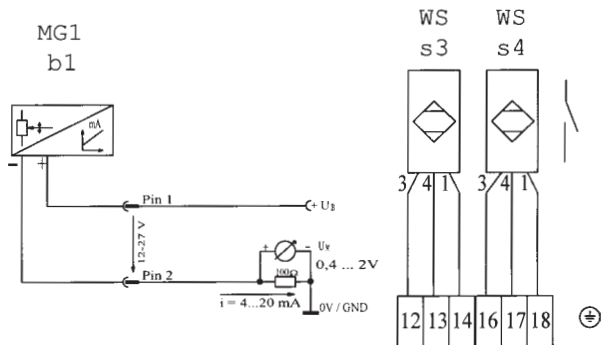


## Switches 2-polar

## way limit switches max. up to 6

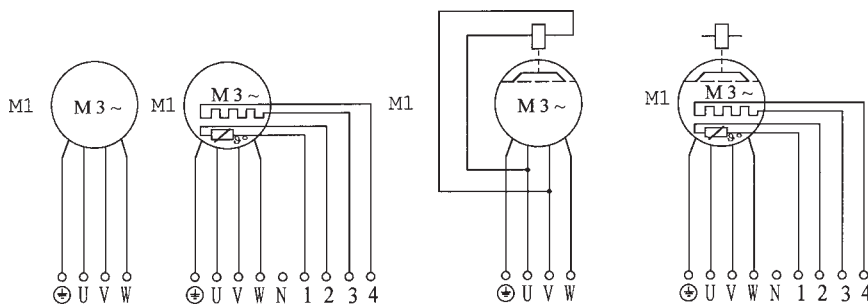


- Legend:
- HVE = Hand wheel with electrical switch off
  - DE = Overload switch
  - WS = Way limit switch
  - POT = Potentiometer
  - DWG = Electronical position repeater  
0-20 mA or 4-20 mA
  - BL = Blinker unit
  - HZ = Heater
  - TW = Thermistor (PTC)
  - MG = Transducer



## Special design:

- Switches gold-plated
- Initiators for shut-down
- Position repeater 4...20 mA



- standard- and breakmotors of all designs
- gearmotors also

# Electronical Supplement

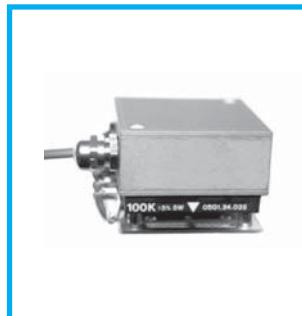
## Way limit switches

To indicate your desired position, we use a control system with two or more switches.



## Electronic position repeating devices

We use electronic position repeating devices 0/4-20 mA as commercial, continuous position indicators.



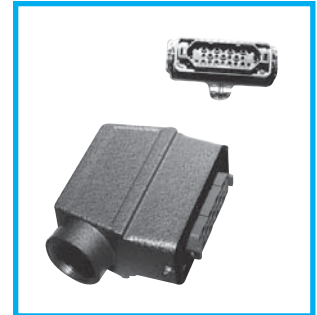
## Micro switch

Special entire moulded switches ensure an ATEX-application.



## Plug connections

For a fast assembly it is of great advantage to use plug connections of commercial manufacturers.



## Potentiometer

It is possible to attach potentiometers for easy and profitable way indication.



## Frequency transformers

Synchronization-, positioning controls and variable speed are possible by using frequency transformers.



# Fax Request

# EUBA

Antriebstechnik  
Eller GmbH  
Fax: +49 201- 8531125

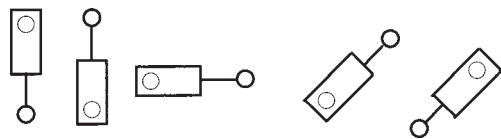
Company:  
Street:  
City:  
Country:  
Phone:  
Fax:  
Interlocutor:

## Regulating power dynamical:

Pull: .....daN  
Push: .....daN  
Static stress: .....daN

Stroke: .....mm  
Velocity: .....mm/s

## Fitting position:



Operating frequency: .....s/h  
Cyclic duration factor: .....% ED

## Type of mounting:

- bracket
- cardan joint
- angle ball+socket joint
- pivot
- flange
- special fixing (on request)
- clevis and bold
- shackle toggle joint+bearing

## Conditions of surroundings:

- dusty
- humid
- tropic
- sea surrounding

## Installation:

- outdoors
- rooved over
- closed room
- ..... meter above sea level

## Specification:

- high rust protection
- special coating
- bellow

Connection voltage: 1AC .....V .....Hz DC .....V  
3AC ...../.....V .....Hz

Enclosure: IP-..... Ambient temperature: .....°C to .....°C  
Insulation class: .....

## Way limit switch:

- 2  4  6 adjustable limit switches
- potentiometer .....Ω
- precision potentiometer .....Ω
- electronic position 0/4 - 20 mA transmitter
- special design (on request)

## Special design:

- PTC thermistor sensor
- brake motor
- anti-condensation heater
- switch box heater
- plug connection

---

## Special features

### Special actuators

EUBA-elektro-actuators of series E4 and F4 are designed for forces up to 2.000.000 N.

Predominantly these actuators are produced for water engineering, iron and steel work et al.

### Explosion protection

Our whole series of actuators can be produced for an operation in explosion-proof constructions zone 22, device category III.

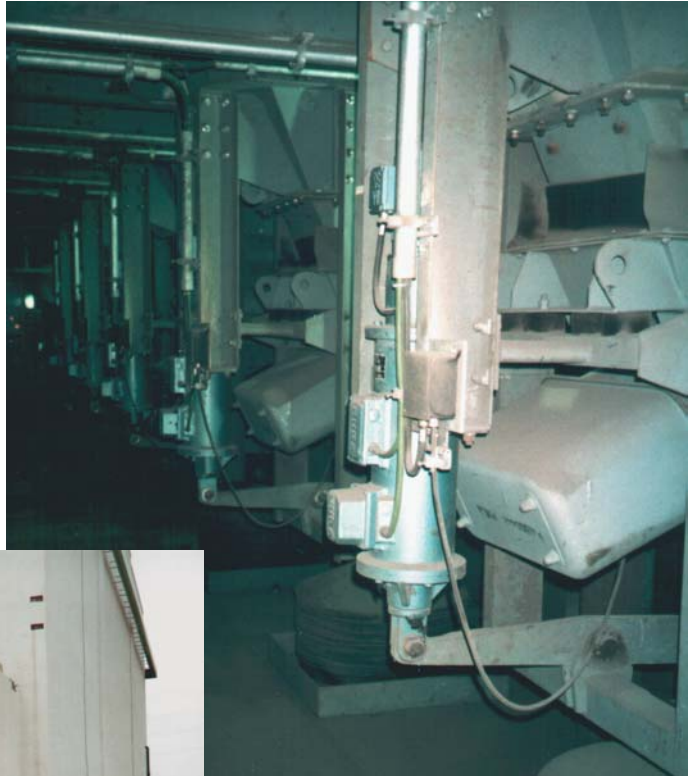
For this we will need detailed information about the job site.

### Synchronous working

By controlling frequency inverters with the help of incremental-/absolute encoders a synchronous working of two or more actuators is ensured.



Accessory drive  
smallest size



Test weight control for  
steel plant



Gate actuator  
Force: 10 t, Stroke: 7000 mm



Road blocker



Cab level regulation  
open-pit lignite mine





Flood gate actuator

Flood gate regulation

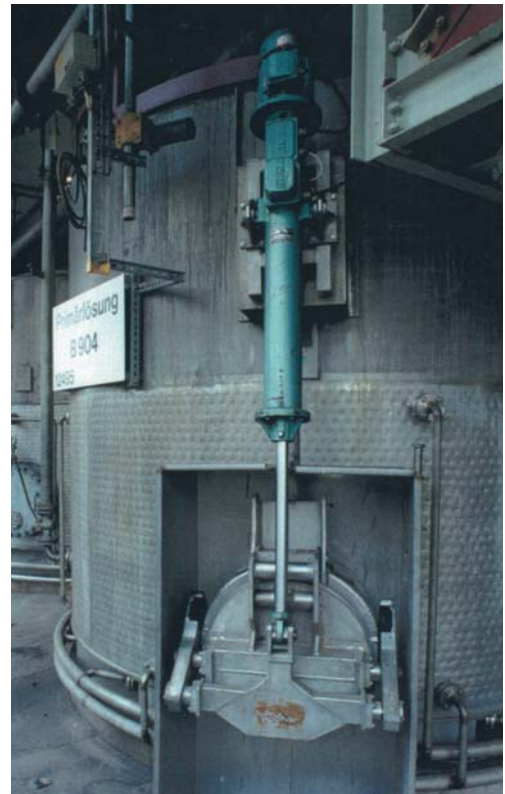


Silo feeding installation for belt conveyor system



Transfer mechanism steel-plant Krivoy-Rok

Damper adjustment



Flood gate actuator

